On a Quasi-Variational Inequality Arising in Semiconductor Theory

José-Francisco Rodrigues(*)

ABSTRACT. Some new mathematical results of existence and uniqueness of solutions are obtained for a class of quasi-variational inequalities modelling the free boundary problem for the determination of the depletion zone in reverse biased semiconductor diodes. The corresponding one (or two) obstacle implicity problems are solved by direct methods with weak regularity estimates for mixed boundary value elliptic problems of second order.

1. INTRODUCTION

The van Roosbroek's model for semiconductor devices consists of an interesting nonlinear diffusion system of equations which has been widely studied in recent years (see, for instance, [MRS] and its references).

For the steady-state case of a $pn$-junction diode under strong reverse bias, after a singular perturbation analysis, the determination of the depletion layer leads to a free boundary problem. For this approximating problem, a double obstacle variational inequality has been proposed for the electrostatic potential $u = u(x)$, which is supposed to be defined for $x \in \Omega \subset \mathbb{R}^N$, where $\Omega$ is a bounded domain representing the semiconductor part of an electronic device (see [HN], [BCM], [S] or [MRS]).

This limit problem consists of finding $u$, such that,

\begin{align}
\psi \leq u \leq \varphi & \quad \text{in } \Omega, \text{ and} \\
-\Delta u = f & \quad \text{in the region } D = \{\psi < u < \varphi\},
\end{align}

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with continuity conditions on the free boundaries \( \partial \{ u = \varphi \} \) and \( \partial \{ u = \psi \} \) and with mixed Dirichlet-Neumann conditions on the fixed boundary \( \partial \Omega \).

In the case of total depletion assumption, \( \varphi \) and \( \psi \) are given constants corresponding to the constant values of the potential at the neutral regions, which are considered then as being fully conducting. In the noncoincidence set \( D \), also called the depletion zone, the potential distribution is governed by the Poisson equation (1.2), where \( f \) models the doping effects. For a singular perturbation analysis of this problem, see [BCM], [BCG] or [Ga] for the one-dimensional case, [CF] for the bidimensional problem with simplified boundary conditions, and [HN], [S] for a discussion of this formal limit problem.

A more complex asymptotic model has been proposed in [NM], where the physical parameters \( \varphi = \varphi (x) \) and \( \psi = \psi (x) \) are the so-called Fermi quasi-potentials, which are functions depending implicitly on the potential \( u \). Actually, in [NM], the domain \( \Omega \) is of the form \( \Omega = \Omega_1 \cup \Gamma \cup \Omega_2 \), where the \( pn \)-junction \( \Gamma \), given by a smooth known interface, separates two simply connected subdomains \( \Omega_1 \) and \( \Omega_2 \). The first one, \( \Omega_1 \), is dominated by the contributions from the negatively charged free electrons (with density \( n = n (x) \)), while the second one, \( \Omega_2 \), by the positively charged holes (with density \( p = p (x) \)).

Under certain simplifying assumptions, in particular, neglecting respectively, in \( \Omega_2 \) and \( \Omega_1 \), the densities

\[
(1.3) \quad n = n_1 \exp [-k_1 (u - \varphi)] \quad \text{and} \quad p = n_2 \exp [-k_2 (u - \psi)];
\]

they may be considered defined only in the subregions \( \Omega_1 \) and \( \Omega_2 \), respectively. Here \( n_1, n_2, k_1, k_2 = -k_1 = k > 0 \) are known physical constants of the model. Then, following [NM], the bilateral condition may be replaced by

\[
(1.4) \quad u \leq \varphi \quad \text{in} \quad \Omega_1 \quad \text{and} \quad u \geq \psi \quad \text{in} \quad \Omega_2,
\]

and in the depletion zone we have

\[
(1.5) \quad -\Delta u = f_1 \quad \text{in} \quad \{ u < \varphi \} \cap \Omega_1 \quad \text{and} \quad -\Delta u = f_2 \quad \text{in} \quad \{ u > \psi \} \cap \Omega_2.
\]

The relation between \( u \) and \( \varphi, \psi \) is given by a nonlinear operator \( u - \{ \Phi (u), \Psi (u) \} \), which is defined by logarithmic transformations of the solutions \( w_1 \) and \( w_2 \) of the following mixed boundary value problems in \( \Omega_1 \) and \( \Omega_2 \), respectively, for \( i = 1, 2 \):

\[
(1.6) \quad \nabla \cdot (e^{-k_i} \nabla w_i) = 0 \quad \text{in} \quad \Omega_i,
\]

\[
(1.7) \quad w_i = e^{k_i} \psi \quad \text{on} \quad \Gamma_i, \quad \frac{\partial w_i}{\partial n} = 0 \quad \text{on} \quad \partial \Omega_i \setminus \Gamma_i.
\]
Here \( \Gamma_i \subset \partial \Omega_i \) is an open subset of the boundary \( \partial \Omega_i \), where the values of \( g_i \) are prescribed in a compatible way with the reverse biased conditions.

The equations (1.6) for \( w_1 \) and \( w_2 \) are derived from the steady-state drift diffusion equations for the negative and positive carrier concentrations, respectively \( n \) and \( p \). Using the relations (1.3), the Fermi quasi-potentials are then given, respectively, by

\[
(1.8) \quad \varphi = \frac{1}{k_1} \log w_1 = \Phi(u) \quad \text{and} \quad \psi = \frac{1}{k_2} \log w_2 = \Psi(u).
\]

This general formulation, with the Fermi quasi-potentials as obstacles in two disjoint subdomains, may be decoupled into two model problems, for mathematical or approximating purposes, as suggested in [NM] or [M]. For instance, taking into account only the effects of carriers of type \( p \), we shall consider first the following implicit unilateral problem in \( \Omega = \Omega_2 \):

\[
(1.9) \quad u \geq \Psi(u), \ -\Delta u \geq f \quad \text{and} \quad (-\Delta u - f) (u - \Psi(u)) = 0 \quad \text{a.e. in } \Omega,
\]

where the obstacle \( \Psi \) is defined by (1.8) and by the solution \( w_2 \) of (1.6)-(1.7).

To complete this formulation we need to add, for instance, a mixed boundary condition of the following type (\( \Gamma_0 \subset \partial \Omega \), \( \Gamma_0 \neq \emptyset \)):

\[
(1.10) \quad u = h \quad \text{on } \Gamma_0 \quad \text{and} \quad \partial u / \partial n = 0 \quad \text{on } \partial \Omega \setminus \Gamma_0.
\]

By applying general results on quasi-variational inequalities (see [M], [BC], [BL], for instance) and using restrictive estimates on \( \nabla u \) in \( L^\infty \), the one-dimensional problem (1.9) and a particular two-dimensional case, with small data, has been considered by Nassif in [N]. Using a direct and, in this case, better approach, which is based on the properties of the obstacle problem (see, e.g., [KS] and [R]) we are able, in Section 2, to solve (1.9)-(1.10) with general assumptions and without any restriction on the space dimension. In Section 3, we discuss sufficient conditions for the uniqueness of the solution with small data, improving the results of [N]. Finally, in Section 4, we extend our results to the model with two obstacles, corresponding to the \( p n \)-junctions case.

2. EXISTENCE OF A SOLUTION TO THE QUASI-VARIATIONAL INEQUALITY

In this section we let \( \Omega \) be a bounded domain of \( \mathbb{R}^N \), for arbitrary \( N \geq 1 \) and with Lipschitz boundary \( \partial \Omega \) if \( N \geq 2 \). We consider the quasi-variational
inequality (1.9) which, incorporating the mixed boundary conditions (1.10), has the form:

\begin{equation}
(2.1) \quad u \in K(u); \quad \int_{\Omega} \nabla u \cdot \nabla (v-u) \, dx \geq \int_{\Omega} f(v-u) \, dx, \quad \forall v \in K(u).
\end{equation}

Here the convex set \( K(u) \) depends on the solution itself through

\begin{equation}
(2.2) \quad K(u) = \{ v \in H^1(\Omega); v = h \text{ on } \Gamma_v \text{ and } v \geq \Psi(z) \text{ in } \Omega \},
\end{equation}

where, for an arbitrary \( z \in L^\infty(\Omega) \), the solution \( w = w(z) \) of the following mixed elliptic problem

\begin{align}
(2.3) & \quad \nabla \cdot (e^{-kz} \nabla w) = 0 \quad \text{in } \Omega, \\
(2.4) & \quad w = e^{kz} \quad \text{on } \Gamma_D \quad \text{and } \quad \partial w / \partial n = 0 \quad \text{on } \partial \Omega \setminus \Gamma_D,
\end{align}

defines the obstacle of (2.2) by the relation

\begin{equation}
(2.5) \quad \Psi(z) = -\frac{1}{k} \log w(z).
\end{equation}

We assume \( k > 0 \) is a given constant, \( \Gamma_v \) and \( \Gamma_D \) are regular, non-empty, open subsets of the boundary \( \partial \Omega \), and \( f, g \) are given functions, such that

\begin{align}
(2.6) & \quad f \in L^{p/2}(\Omega) \quad \text{and} \quad g, h \in W^{1,p}(\partial \Omega) \quad \text{for some } p > N > 1, \quad \text{and} \\
& \quad f \in L^1(\Omega) \quad \text{and} \quad g, h \quad \text{take constant values, for } N = 1.
\end{align}

Lemma 2.1 For any \( z \in L^\infty(\Omega) \), there exists a unique \( w = w(z) \in H^1(\Omega) \cap C^{0,\alpha}(\Omega) \), for some \( 0 < \alpha \leq 1 - N/p \), solving (2.3)-(2.4). Moreover \( w \) satisfies the estimates

\begin{align}
(2.7) & \quad 0 < e^{kz} = \inf_{z_1} e^{kz} \leq w \leq e^{kz} = \sup_{z_2} e^{kz} \quad \text{in } \Omega, \\
(2.8) & \quad \| w(z_i) - w(z_2) \|_{H^1(\Omega)} \leq C \| z_i - z_2 \|_{L^\infty(\Omega)}
\end{align}

where \( C > 0 \) depends on \( \| z_1 \|_{L^\infty(\Omega)} \) and \( \| z_2 \|_{L^\infty(\Omega)} \).

Proof: Noting that, for \( z \in L^\infty(\Omega) \), we have

\begin{equation}
0 < \zeta^* = \inf_{\Omega} e^{-kz} \leq e^{-kz} \leq \zeta^* = \sup_{\Omega} e^{-kz} \quad \text{in } \Omega,
\end{equation}
The first part of this lemma is immediate by the elliptic theory, the Hölderian estimates up to the boundary (note that \( g \in C^{0,1-N/p}(\partial \Omega) \)) and the maximum principle.

To prove (2.8) we write (2.3)-(2.4) in variational form for \( w_i = w(z_i) \):

\[
\int_{\Omega} e^{-k_2} \nabla w_i \cdot \nabla v \, dx = 0, \quad \forall \, v \in H^1(\Omega), \quad v|_{\Gamma_0} = 0, \text{ for } i = 1, 2,
\]

and we take \( v = w_1 - w_2 \equiv \bar{w} \); letting \( \zeta_1 = \inf_{\Omega} e^{-k_2} > 0 \), we obtain

\[
\zeta_1 \| \nabla \bar{w} \|^2_{L^2(\Omega)} \leq \int_{\Omega} e^{-k_2} |\nabla \bar{w}|^2 \, dx = \int_{\Omega} (e^{-k_2} - e^{-k_1}) \nabla w_2 \cdot \nabla \bar{w} \, dx
\]

\[
= \| e^{-k_1} - e^{-k_2} \|_{L^\infty(\Omega)} \| \nabla w_2 \|_{L^2(\Omega)} \| \nabla \bar{w} \|_{L^2(\Omega)}.
\]

Since \( \| \nabla w_2 \|_{L^2(\Omega)} \) is bounded by some constant depending on \( \| w_1 \|_{L^\infty(\Omega)} \) and on \( \| g \|_{H^{1/2}(\partial \Omega)} \), from (2.9) we easily obtain the estimate (2.8), recalling the Poincaré inequality for \( \bar{w} = w(z_1) - w(z_2) \).

**Remark 2.1** The global estimates of De Giorgi-Stampacchia imply that the bound on \( \| w \|_{C^{0,\alpha}(\Omega)} \) depends only on the constants \( \zeta_1, \zeta^* \) and the Dirichlet data \( g \) (see, e.g., [R], page 170, and its references). Hence as an immediate consequence of (2.8), the nonlinear mapping \( z \rightarrow w(z) \) is sequentially continuous from \( L^\infty(\Omega) \) into \( H^1(\Omega) \cap C^{0,\alpha}(\Omega) \) for any \( 0 \leq \alpha' < \alpha \), for some fixed \( \alpha' \).

As an immediate consequence of Lemma 2.1 and Remark 2.1, we can state:

**Lemma 2.2** For any \( z \in L^\infty(\Omega) \), the obstacle \( \Psi = \Psi(z) = \frac{1}{k} \log w(z) \) is, such that, \( \Psi \in H^1(\Omega) \cap C^{0,\alpha}(\Omega) \), for some \( 0 < \alpha \leq 1 - \frac{N}{p} \), \( \Psi = g \) on \( \Gamma_0 \) and

\[
\eta_0 \leq \Psi \leq \eta^* \text{ in } \Omega, \text{ independently of } z \in L^\infty(\Omega).
\]

In addition, the mapping \( \Psi : z \rightarrow \Psi(z) \) is sequentially continuous from \( L^\infty(\Omega) \) into \( H^1(\Omega) \cap C^{0,\alpha}(\Omega) \) for any \( 0 \leq \alpha' < \alpha \), i.e., if \( z_n \rightarrow z \) in \( L^\infty(\Omega) \) then \( \Psi(z_n) \rightarrow \Psi(z) \) in \( H^1(\Omega) \cap C^{0,\alpha}(\Omega) \).
In order to solve (2.1) we consider, for any $z \in L^\infty(\Omega)$, the auxiliary obstacle problem

$$u_0 \in K(z): \int \nabla u_0 \cdot \nabla (v - u_0) \, dx \geq \int f(v - u_0) \, dx, \quad \forall v \in K(z),$$

and we recall some well-known properties of the translated problem:

$$\tilde{u} \in K_{\tilde{\psi}}: \int \nabla \tilde{u} \cdot \nabla (v - \tilde{u}) \, dx \geq 0, \quad \forall v \in K_{\tilde{\psi}}.$$

Here, if we suppose $\tilde{\psi} \in H^1(\Omega)$, such that, $\tilde{\psi} \leq 0$ on $\Gamma_0$, we have

$$K_{\tilde{\psi}} = \{ v \in H^1(\Omega) : v = 0 \text{ on } \Gamma_0 \text{ and } v \geq \tilde{\psi} \text{ in } \Omega \}. \neq \emptyset.$$

Using the standard notations $\Lambda$ and $V$ for $\inf$ and $\sup$, respectively, we recall the following results:

**Proposition 2.1** For each $\tilde{\psi} \in H^1(\Omega) \cap L^\infty(\Omega)$, $\tilde{\psi} \leq 0$ on $\Gamma_0$ there exists a unique solution $\tilde{u}$ of (2.12) verifying the estimate

$$0 \leq \tilde{u} \leq 0 \text{ sup } \tilde{\psi} \text{ in } \Omega.$$

Moreover the corresponding mapping $\tilde{\psi} \rightarrow \tilde{u}(\tilde{\psi})$ is sequentially continuous from $H^1(\Omega)$ into $H^1(\Omega)$ and a contraction in $L^\infty(\Omega)$:

$$\| \tilde{u}(\psi_1) - \tilde{u}(\psi_2) \|_{L^\infty(\Omega)} \leq \| \psi_1 - \psi_2 \|_{L^\infty(\Omega)}.$$

**Proof:** See, e.g., [R], Chap 4.

The reduction of the problem (2.11) to (2.12) is done by considering the mixed linear problem:

$$-\Delta \xi = f \text{ in } \Omega, \quad \xi = h \text{ on } \Gamma_0, \quad \partial \xi / \partial n = 0 \text{ on } \partial \Omega \setminus \Gamma_0.$$

By $C^{0,\alpha}$ —estimates, we know that the unique solution of (2.16) satisfies, for some constant $C > 0$ and some $0 < \alpha \leq 1 - N/p$ (recall (2.6)):

$$\mu = \| \xi \|_{C^{0,\alpha}(\Omega)} \leq C (\| f \|_{L^p(\Omega)} + \| h \|_{W^{1,p}(\partial \Omega)}).$$
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Then, letting \( \tilde{u} = u - \xi \) and \( \tilde{\psi} = \Psi(z) - \xi \) we establish the equivalence between (2.11) and (2.12), for every fixed \( z \in L^\infty(\Omega) \), such that, \( K(z) \neq \emptyset \). This compatibility condition can be guaranteed, for instance, by assuming

\[
\inf_{\Gamma_0 \setminus \Gamma_D} h \geq \sup_{\Gamma_0} g \quad \text{and} \quad g \leq h \quad \text{on} \quad \Gamma_0 \cap \Gamma_D.
\]

(2.18)

**Lemma 2.3.** Assuming (2.6) and (2.18), for any \( z \in L^\infty(\Omega) \), there exists a unique \( u_\ast \in K(z) \cap C^0(\Omega) \), for some \( 0 < \gamma < 1 \), solving (2.11) which satisfies the estimate

\[
\eta_\ast \leq u_\ast \leq 2\mu + \eta^* \quad \text{in} \quad \Omega, \quad \text{independently of} \quad z.
\]

Moreover, the mapping \( z \rightarrow u_\ast \) is sequentially continuous from \( L^\infty(\Omega) \), into \( H^1(\Omega) \cap C^0(\Omega) \), \( 0 \leq \gamma^* < \gamma \), and it satisfies

\[
\| u_\ast - u_0 \|_{C^0(\Omega)} \leq \| \Psi(z) - \Psi(\tilde{z}) \|_{C^0(\Omega)}.
\]

(2.19)

**Proof:** Due to the equivalence of (2.11) and (2.12), we need to guarantee the admissibility condition \( K(z) \neq \emptyset \), i.e.,

\[
\tilde{\psi} = \Psi(z) - h \leq 0 \quad \text{on} \quad \Gamma_0, \quad \text{independently of} \quad z \in L^\infty(\Omega).
\]

Since \( \Psi(z) = g \) on \( \Gamma_0 \), of course that condition is always verified if \( \Gamma_0 \subset \Gamma_D \), but in general, we only know that, in \( \Omega \),

\[
\inf_{\Gamma_0} g = \eta_\ast \leq \Psi(z) \leq \sup_{\Gamma_0} g, \quad \text{for all} \quad z \in L^\infty(\Omega),
\]

and this is the reason to require the sufficient condition (2.18).

Recalling the Hölder continuity of the solutions of the obstacle problem (see [R], Section 5:7) and the Proposition 2.1, we complete the proof of this lemma by noting that for \( u_\ast = \tilde{u} + \xi \) we have:

\[
\Psi(z) \leq u_\ast \leq \xi + \sup_{\Omega} \{ \Psi(z) - \xi \}^*.
\]

**Remark 2.2** The assumption (2.18) is satisfied in the physical situation considered in [N], where \( \Gamma_D \subset \Gamma_n \) and \( g \) traduces the reverse-biased conditions (\( g > 0 \) on \( \Gamma_D \setminus \Gamma_p \) and \( g \leq 0 \) on \( \Gamma_D \)). Notice that, in [N], \( u \) and \( g \) were considered with the opposite signs, corresponding to an upper obstacle, as for the case of carriers of type \( n \) only.
Theorem 2.1  Under the assumptions (2.6) and (2.18), there exists at least a solution $u$ to the quasi-variational inequality (2.1). Moreover, $u$ has the regularity
\begin{equation}
    u \in C^0,\gamma (\Omega) \cap W^{2,\infty}_{\text{loc}}(\Omega), \text{for some } 0 < \gamma < 1.
\end{equation}

Proof: The solution $u$ is given by any fixed point of the mapping $T: z \rightarrow u_z$, defined by the auxiliary problem (2.11). Using the "a priori" estimate (2.19), we consider as domain of $T$ the convex set:
\begin{equation}
    M = \{ v \in C^0(\Omega): \eta_* \leq v \leq 2\mu + \eta^* \text{ in } \Omega \}
\end{equation}
of the Banach space $C^0(\Omega)$. Since Lemma 2.3 yields $T(M) \subset M \cap C^{0,\gamma}(\Omega)$, by the compactness of $C^{0,\gamma}(\Omega) \subset C^0(\Omega)$, the Schauder fixed point theorem guarantees the existence of $u = Tu$.

Since $u \in C^{0,\gamma}(\Omega)$, by local regularity of the solution of the equation (2.3), we find $w(u) \in C^{1,\gamma}(\Omega)$ and then also $\Psi(u) \in C^{1,\gamma}(\Omega)$. Hence, by the local regularity of the obstacle problem, we have also $u \in C^{1,\gamma}(\Omega)$ and, by iterating once, it follows $w(u)$ and $\Psi(u)$ in $C^{2,\gamma}(\Omega)$, which is then sufficient to obtain the optimal regularity $u \in W^{2,\infty}_{\text{loc}}(\Omega)$ (see, e.g., [R]).

Remark 2.3 This existence result considerably extends [N], which only covered the cases $N = 1$ and $N = 2$ with piecewise constant $g$, with $0 \leq f \in L^\infty(\Omega)$ and with a very restrictive smallness condition on $g$. This was due to the method of [N] that required an "a priori" estimate on $\|\nabla w\|_{L^\infty(\Omega)}$, which in general does not hold for the mixed problem (2.3)-(2.4).

3. UNIQUENESS OF SOLUTIONS FOR SMALL DATA

The existence of a solution in the preceding section does not require any restriction on the size of the data, since it was based on the Schauder fixed point theorem. For the same mapping $T: z \rightarrow u_z$, we investigate now sufficient conditions in order to make $T$ a strict contraction in the metric space $M$, defined in (2.22). This will imply the uniqueness of the solution, by the Banach fixed point theorem. It turns out, that it is sufficient to improve the Lipschitz dependence (2.8) for the solution $w$ of the mixed boundary value problem (2.3)-(2.4), with respect to $z$.

For $p > N$ and if $\Gamma_D \subset \partial \Omega$ has positive $(N-1)$-measure, we recall that, by the Poincaré and Sobolev inequalities, we have
\begin{equation}
    \|v\|_{C^0(\overline{\Omega})} \leq C_p \|\nabla v\|_{L^p(\Omega)} \quad \text{for all } v \in W^{1,p}_{\text{loc}}(\Omega),
\end{equation}
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where $C_p = C(p, N, \Omega, \Gamma_D) > 0$ is a fixed constant, and $W^{1,p}_0(\Omega)$ is the closure of the set $\{ v \in C^1(\Omega) : \text{supp } v \cap \Gamma_D = \emptyset \}$ in the Sobolev space $W^{1,p}(\Omega)$. Note that the trace $v|_{\Gamma_D} = 0$, for every $v \in W^{1,p}_0(\Omega)$.

**Theorem 3.1** Under the assumptions of Section 2, namely (2.6) and (2.18), suppose the solution map $z \rightarrow w(z)$, associated to the problem (2.3)-(2.4), applies $M$ into $W^{1,p}(\Omega)$ and, for some $p > N$ and some constant $\lambda = \lambda (M, k, g, \Omega, \Gamma_D, \mu) > 0$:

$$||\nabla w(z_1) - \nabla w(z_2)||_{L^p(\Omega)} \leq \lambda ||z_1 - z_2||_{C(\Omega)}.$$  \hfill (3.2)

Then there exists a unique solution $u$ to (2.1), provided the data are such that:

$$\lambda C_p e^{-k\eta} / k < 1.$$  \hfill (3.3)

**Proof** Recalling (2.5) and (2.7) we have, for $\psi_i = \Psi(z_i)$ and $w_i = w(z_i)$, $i = 1, 2$,

$$||\psi_1 - \psi_2||_{C(\Omega)} \leq \frac{1}{k} \left| \log w_1 - \log w_2 \right| \leq \frac{1}{k} \sup_{z \in \Omega} \frac{1}{w(z)} \left| w_1 - w_2 \right|.$$  \hfill (3.1)

hence, using (2.15), (3.1) and (3.2) we obtain, for $u_i = u(z_i)$,

$$||u_1 - u_2||_{C(\Omega)} \leq ||\psi_1 - \psi_2||_{C(\Omega)} \leq (e^{-k\eta} / k) ||w_1 - w_2||_{C(\Omega)}$$

$$\leq (e^{-k\eta} / k) C_p ||\nabla (w_1 - w_2)||_{L^p(\Omega)} \leq \delta ||z_1 - z_2||_{C(\Omega)},$$

where $\delta = C_p (e^{-k\eta} / k) \lambda < 1$. Therefore $T : z \rightarrow u$, is a strict contraction in $M$ and the conclusion follows.

We discuss now three cases where the estimate (3.2) holds. First, for $N = 1$ it is immediate that (3.2) holds with $p = 2$, from the estimate (2.8). We can be more precise on the smallness condition (3.3) if we specify our problem, as in [N], for instance:

$$\Omega = J, \quad \Gamma_0 = \Gamma_D = \partial \Omega \quad \text{and} \quad -v = g(0) < g(\xi) = 0 = h(0) < h(\xi) = \beta.$$  \hfill (3.4)

In this case, we can compute $\lambda$ in the following way: noting that $-\nu \leq z_2 \leq 2\mu$ we have an "a priori" bound on $||w_2||_{L^2(\Omega, \partial \Omega)}$, from

$$\int_0^{e^{-k\mu}} \int_{\Omega} |w_2|^2 \, dx \leq \int_0^{e^{-k\mu}} \int_{\Omega} |w_2|^2 \, dx = (1 - e^{-k\mu}) \int_0^{e^{-k\mu}} w_2 \, dx \leq (e^{k\mu} - 1) \sqrt{\mu} \left( \int_{\Omega} |w_2|^2 \, dx \right)^{1/2}$$

In this case, we can compute $\lambda$ in the following way: noting that $-\nu \leq z_2 \leq 2\mu$ we have an "a priori" bound on $||w_2||_{L^2(\Omega, \partial \Omega)}$, from
(by using the test function \( v(x) = (1 - e^{-k \psi}) x^r + e^{-k \psi} - w_2 \)); which, introduced in (2.9) with \( \xi = e^{-2k \psi} \), yields (3.3) with \( p = 2 \) and

\[
\lambda = ke^{k(\delta + \psi)}(e^{k \psi} - 1)/\sqrt{r}.
\]

Noting that we can take now \( C_\delta = \sqrt{r} \) in (3.1) and \( \eta = 0 \) we may choose \( \delta = (e^{k \psi} - 1) e^{k(\delta + \psi)} \) and we have the following consequence of Theorem 3.1:

**Corollary 3.1** In the one dimensional case (3.4), there exists a unique solution of (2.1), provided \( (e^{k \psi} - 1) e^{k(\delta + \psi)} < 1 \).

**Remark 3.1** Note that \( \mu \), defined in (2.17), depends on \( f \) and on \( \beta \). We observe that if, as in the physical case, \( f \leq 0 \), by Theorem 4.5.4 of [R] applied to (1.11), we may replace \( 2 \mu \) exactly by \( \beta \), yielding, in particular, the "\( a \ priori \)" estimate \(-v \leq u \leq \beta \). As a consequence, with the sufficient condition \( (e^{k \psi} - 1) e^{k(\delta + \psi)} < 1 \), that is to say, for sufficiently small values of the potentials \( \beta \) and \( \psi \), we have uniqueness of solutions near the stable equilibrium null state. Corollary 3.1 yields a much more accurate uniqueness criteria than the previous one of [N].

For the mixed problem in higher dimensions the estimate (3.2) for \( p > N \) is a delicate question. However the extension of Meyers estimate, recently given in [G], to the mixed problem yields an interesting application to the bidimensional case.

**Corollary 3.2** Let \( N = 2 \) and suppose that the Lipschitz boundary \( \partial \Omega \) is decomposed into \( \Gamma_D \) and \( \partial \Omega \setminus \Gamma_D \) with \( \Gamma_D \cap (\partial \Omega \setminus \Gamma_D) \) consisting of a finite number of points. Then, for sufficiently small data, in particular, if the Dirichlet data \( g \) has small variation, there exists a unique solution of the quasi-variational problem (2.1).

**Proof** Let \( \tilde{g} \in W^{1, p}(\Omega), \) for \( p > 2, \) be an extension of the boundary data. Then the variational solution \( \tilde{w} \) of the mixed problem (2.3)-(2.4) may be given by \( \tilde{w} = \bar{w} + e^{-k \psi} \), where \( \bar{w} \) is the unique solution of

\[
(3.5) \quad \tilde{w} \in W^{1, 2}_{\text{loc}}(\Omega): \int_{\Omega} e^{k \psi} \nabla \tilde{w} \cdot \nabla v dx = \int_{\Omega} F \cdot \nabla v dx, \quad \forall v \in W^{1, 2}_{\text{loc}}(\Omega),
\]

with \( F = k e^{k(\psi - \beta)} \nabla \tilde{g} \in [L^p(\Omega)]^2, \) for \( p > 2 \) and for each \( z \in M \).

Since \( z \in M, \) from Theorem 1 of [G], there exists a \( q, 2 < q \leq p, \) and a constant \( L_q = L(q, \Omega, \Gamma_D, \xi, \xi') > 0, \) such that,

\[
(3.6) \quad \| \nabla \tilde{w} \|_{L^q(\Omega)} \leq L_q \| F \|_{L^q(\Omega)} \leq k L_q \sup_{\Omega} e^{k(\psi - \beta)} \| \nabla \tilde{g} \|_{L^q(\Omega)}.
\]
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Considering now \( w_1 = w(z_1) \) and \( w_2 = w(z_2) \), we easily see that \( \bar{w} = w_1 - w_2 \) is also the solution of (3.5), now with \( z \) replaced by \( z_1 \) and \( F \) by \( \bar{F} = (e^{k_2} - e^{k_1}) \nabla w_2 \in [L^q(\Omega)]^R \), by (3.6). Analogously we obtain, for some \( r, 2 < r \leq q \):

\[
\|\nabla \bar{w}\|_{L^r(\Omega)} \leq L_r \|\nabla \bar{F}\|_{L^r(\Omega)} \leq L_r \|e^{k_2} - e^{k_1}\|_{L^r(\Omega)} \|\nabla w_2\|_{L^q(\Omega)}
\]

(3.7)

This yields an expression for \( \lambda \) in the corresponding estimate (3.2), which implies the conclusion of this Corollary.

Remark 3.2. This existence and uniqueness result holds, in particular, in any domain which boundary is piecewise of class \( C^1 \) and whose vertices are not cusps, as for instance, in any polygonal domain. A more restrictive result was presented in [N], for a rectangular domain, in which Grisvard's results for elliptic equations with mixed boundary conditions yields a \( H^2(\Omega) \cap W^{1,m}(\Omega) \) solutions for (2.3)-(2.4) (see [N] or [R], for references).

Nevertheless if \( \partial \Omega \setminus \Gamma_D = \emptyset \) in (2.4), the regularity of the Dirichlet problem holds for every \( W_0^1(\Omega) \) and we can state the following result.

Corollary 3.3 For arbitrary dimension \( N \), if \( \Gamma_D = \partial \Omega \) is of class \( C^1 \) and (2.6) and (2.18) hold, then there exists an \( \varepsilon_0 > 0 \), such that, if

\[
\|g\|_{W^{1,p}(\partial \Omega)} \leq \varepsilon_0, \text{ for some } p > N,
\]

there exists a unique solution of (2.1).

Proof: Using the \( W_0^1(\Omega) \)-regularity of the homogeneous Dirichlet problem (3.5) in \( H^2(\Omega) \) (see, e.g., Thm. 3.7.2 of [R] and its references) and arguing as in the previous Corollary, we have (3.6) and (3.7) for \( q = r = p > N \). Then the conclusion is immediate, by recalling the corresponding dependence of \( \lambda \) on \( g \) and the condition (3.3).

4. APPLICATION TO REVERSE BIASED \( pn \)-JUNCTIONS

In this section we extend the existence and uniqueness results for the model problem (2.1) to the following similar quasi-variational inequality corresponding to the \( pn \)-junction model (1.4)-(1.5):

\[
(4.1) \quad u \in C(u): \int_{\Omega} \nabla u \cdot \nabla (v - u) \, dx \geq \int_{\Omega} f(v - u) \, dx, \quad \forall v \in C(u),
\]
Here we suppose $\Omega = \Omega_1 \cup \Gamma \cup \Omega_2$ is a Lipschitz domain, such that, each subdomain $\Omega_1$ and $\Omega_2$ have also Lipschitz boundaries $\partial \Omega_1$ and $\partial \Omega_2$, with $\Gamma = \partial \Omega_1 \cap \Omega = \partial \Omega_2 \cap \Omega \neq \emptyset$. Accordingly, we choose $f = f_1$ on $\Omega_1$ and $f = f_2$ on $\Omega_2$ and we define, for each $z \in L^\infty(\Omega)$ and for $\Gamma_0 \subset \partial \Omega$ ($\Gamma_0$ open, $\Gamma_0 \neq \emptyset$)

\begin{equation}
C(z) = \{ v \in H^1(\Omega): v = h \text{ on } \Gamma_0, \ v \leq \Phi(z) \text{ in } \Omega_1 \text{ and } v \geq \Psi(z) \text{ in } \Omega_2 \},
\end{equation}

where $z - \{ \Phi(z), \Psi(z) \}$ is given by (1.8), with the auxiliary mixed problem (1.6)-(1.7), with $z$ instead of $u$ and with

\begin{equation}
\Gamma_i \subset \partial \Omega \setminus \Gamma, \ \Gamma_i \neq \emptyset, \ g|\Gamma_i = g_0, \ \text{for } i = 1, 2 \text{ and } -k_1 - k_2 = k > 0.
\end{equation}

As in the case of only one obstacle, it is necessary to guarantee that $C(z) \neq \emptyset$, independently of $z$. In a similar way to the assumption (2.18) we shall require the natural compatibility conditions:

\begin{equation}
g \geq h \text{ on } \Gamma_1 \cap \Gamma_0 \text{ and } \inf_{\Gamma_1} g \geq \sup_{\Gamma_1 \cap (\partial \Omega_1) \setminus \Gamma_1} h;
\end{equation}
\begin{equation}
g \leq h \text{ on } \Gamma_2 \cap \Gamma_0 \text{ and } \sup_{\Gamma_2} g \leq \inf_{\Gamma_2 \cap (\partial \Omega_2) \setminus \Gamma_2} h;
\end{equation}

and the mathematical expression of the reverse biased conditions:

\begin{equation}
\sup_{\Gamma_2} g \leq 0 \leq \inf_{\Gamma_1} g.
\end{equation}

**Theorem 4.1** Under the preceding assumptions, namely (4.3)-(4.6) and (2.6), the quasi-variational inequality (4.1)-(4.2) has at least one solution, with the regularity

\begin{equation}
u \in C^{0,\gamma}(\overline{\Omega} \cap W^{1,\infty}_{\text{loc}}(\Omega_1 \cup \Omega_2), \text{ for some } 0 < \gamma < 1.
\end{equation}

**Proof:** Since the proof follows the same lines of the one of Theorem 2.1, we only sketch it, referring the necessary changes. We find the solution $u$ as a Schauder fixed point for $T: Z \ni z \rightarrow u_z \in Z$, defined by the auxiliary problem (2.11) with $K(z)$, replaced by $C(z)$; the corresponding double obstacle problem can be reduced, using (2.15), to the simpler problem (2.12) for $\tilde{u} = u_z - \xi$, where $K_{\tilde{u}}$ is now replaced by $K_{\tilde{u}} = \{ v \in H^1(\Omega): v = 0 \text{ on } \Gamma_0, \ v \leq \phi \in \Omega_1 \text{ and } v \geq \psi \text{ in } \Omega_2 \};$ the assumptions (4.4) and (4.5) imply $\tilde{\phi} = \phi(z) - h \geq 0$ and $\tilde{\psi} = \psi(z) - h \leq 0$ on $\Gamma_0$, independently of $z$; while (4.6), by the maximum principle for (1.6)-(1.7), implies, through (1.8), the conditions $\Phi(z) \geq 0$ in $\Omega_1$ and $\Psi(z) \leq 0$ on $\Omega_2$; hence $K_{\tilde{u}} \neq \emptyset$ and also $C(z) \neq \emptyset$ independently of $z$; since the analogous of Proposition 2.1 holds for this double obstacle
problem, it yields \( \inf_{\Omega_1} \phi \leq \bar{u} \leq \inf_{\Omega_2} \psi \) in \( \Omega \), which implies the "a priori" estimate for \( u_i \):

\[
\xi_i = \inf_{\Omega_i} g - 2\mu \leq u_i \leq \sup_{\Omega_i} g + \xi_i \quad \text{in } \Omega;
\]

these bounds are, of course, independent of \( z \), and they can be used to define \( Z = \{ \gamma \in C^0(\Omega) : \xi_1 \leq \gamma \leq \xi_2 \text{ in } \Omega \} \). Using the Hölder continuity of each solution and their respective continuous dependence results, the conclusion follows similarly, as well as the local \( W^{2,m} \)-regularity in \( \Omega_i \) and in \( \Omega_2 \).

Under similar assumptions, as in Section 3 we can give sufficient conditions on the smallness of the data so that the nonlinear mapping \( T : z \rightarrow u_i \) is a strict contraction.

Denote by \( C_i = C_i(\Omega_i) \) the corresponding Sobolev constant of (3.1) for functions of \( W^{1,p}_i(\Omega_i) \), \( p > N \) (\( i = 1, 2 \)). Suppose the solution mappings \( z \rightarrow w_i(z) \), associated with each problem (1.6)-(1.7), apply \( Z \) into \( W^{1,p}(\Omega_i) \) and, analogously to (3.2), we have, for some \( \lambda_i > 0 \),

\[
\| \nabla w_i(z) - \nabla w_i(\bar{z}) \|_{L^p(\Omega_i)} \leq \lambda_i \| z - \bar{z} \|_{C^{0,\alpha}(\Omega_i)}, \quad i = 1, 2.
\]

Notice that, if \( u = u(z) \) and \( \bar{u} = u(\bar{z}) \) denote the (unique) solutions of (2.11), respectively, in \( C(z) \) and \( C(\bar{z}) \) (with the definition (4.2)), the analogous of (2.20) holds in the following form:

\[
\| u - \bar{u} \|_{C^{0,\alpha}(\Omega)} \leq \Phi(z) - \Phi(\bar{z}) \|_{C^{0,\alpha}(\Omega)} \| \Psi(z) - \Psi(\bar{z}) \|_{C^{0,\alpha}(\Omega)}
\]

Recalling that \( w_i \geq \inf_{\Omega_i} e^{k_i} \), and the definitions (1.8), as in the proof of Theorem 3.1, we easily deduce

\[
\| u - \bar{u} \|_{C^{0,\alpha}(\Omega)} \leq \delta \| z - \bar{z} \|_{C^{0,\alpha}(\Omega)}
\]

with \( \delta = (e^{k_1} C_1 \lambda_1 / k) \vee (e^{k_2} C_2 \lambda_2 / k), \quad \eta_1 = \sup_{\Omega_i} g \) and \( \eta_2 = \inf_{\Omega_i} g \), and the following theorem is then proved.

**Theorem 3.2** Under the above assumptions, namely (2.6), (4.3)-(4.6) and (4.8), there exists a unique solution \( u \) to (4.1), for sufficient small data, namely, if the following conditions holds

\[
(e^{k_{11}} C_1 \lambda_{11} / k) \vee (e^{k_{21}} C_2 \lambda_{21} / k) < 1.
\]
Remark 4.1 As in the Corollary 3.1, for the simple case of one space dimension, with Dirichlet data, the estimate (4.9) can be made more precise by imposing further specifications into our problem.

Remark 4.2 Also the Corollary 3.2 has its natural extension to the corresponding bidimensional model for pn-junctions, by applying the $W^{1, p}$-regularity estimate for mixed problems to both subdomains $\Omega_1$ and $\Omega_2$, which yields the required estimates (4.8) for some $p > 2 = N$.

Remark 4.3 The extension of the $N$-dimensional case of Corollary 3.3 is also possible with the following change in the first part of the assumption (4.3): for each $i = 1, 2$, suppose $\partial \Omega_i = \Gamma_i$ of class $C^1$ and $\Gamma_1 \cap \Gamma_2 = \Gamma$, with $\Gamma \cap \partial \Omega = \emptyset$; hence the $W^{1, p}$-regularity holds for each Dirichlet problem in $\Omega_1$ and $\Omega_2$.

References


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CMAF-INIC and Univ. of Lisbon
Av. Prof. Gama Pinto, 2
1699 LISBOA CODEX (PORTUGAL)  
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